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Differential dynamic programming (DDP) is an optimal control algorithm of the trajectory optimization class. The algorithm was introduced in 1966 by Mayne and subsequently analysed in Jacobson and Mayne's eponymous book. The algorithm uses locally-quadratic models of the dynamics and cost functions, and displays quadratic convergence. It is closely related to Pantoja's step-wise Newton's method.

Differential dynamic programming - Wikipedia

ional Dynamic Programming where the optimal cost function is considered globally,, Differential. Dynamic Programming applies the principle of optimality in the neighbourhood of a-nominal, possibly non-optimal, trajectory. Mayne [15] introduced the notation of "Differential Dynamic Programming" and Jacobson [10,11,12] developed it

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several independent variables; however, is more complex. The calculus of variations yields partial differential equations while dynamic programming yields functional differential equations, the Gateaux equation. 2. THE VARIATIONAL PROBLEM We consider the problem of minimizing the functional; $J(u) = \int q(u, u') dt$

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